
A Dynamical Systems Model for Face Perception

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Abstract: The fusiform face area, or FFA, is a small region found on the inferior (bottom) surface of the temporal lobe. It is located in a gyrus called the fusiform gyrus. Studies in humans have shown that the FFA is sensitive to both face parts and face configurations. Recoding activity in the FFA showed that most of the neurons in the FFA are active in response to facial imagery, but not in response to images of other body parts or objects. Visual sensory neurons sensitive to a face feature and possessing a related firing rate activate an associated cluster of neurons in the FFA. This results in a partition of the FFA into clusters that respond to the various facial features. Once an entire face stimulus activates the FFA, interneurons redistribute the initial activation via the neural network. In this article a novel approach to modelling the function of the network is presented. We define by a transition matrix that describes probabilistically how one cluster, firing at a synchronous rate, affects the others in the FFA. The initial face stimulation in the FFA together with the transition matrix defines a dynamical system which possesses a stationary probability function. We claim that a stationary probability function uniquely represents a face. Among the properties of this probability function are: 1) response magnitude invariance, 2) repurposing of clusters to define new stationary probability function on the FFA partition; 3) stability of stationary probabilities under perturbations.

Keywords: Dynamical Systems, Model for Face Perception, Fusiform Face Area (FFA), Face Parts, Stationary Measure, Stability

1. Introduction

The neural correlates of human face perception are in the fusiform face area (FFA) [13]. The FFA is also implicated in "extracting the perceptual information used to distinguish between faces" [13]. The visual sensory neurons that perceive different facial features terminate in different clusters or patches in the FFA [16], from where they activate other neurons [22] via the neural network of the FFA. We assume that to each feature there corresponds a specific firing rate as has been proven in the primate brain [8]. The model in [8] formats a face in a very high dimensional space. Using 50 axes, it takes as many as 2500 numbers to characterize a face. In our model, we typically deal with clusters of the order of 10, and characterize a face by a probability function on these clusters. Hence, much less information is needed to represent a face than in [8].

We label n facial features as F_1, \dots, F_n . and $C = \{C_i, i = 1, \dots, n\}$ as the associated activated clusters in the FFA. This

forms a partition of the FFA as depicted in Figure 1. Once an entire face stimulus - coming simultaneously and in parallel from the n facial features - arrives at the FFA, the interneuron cells in the FFA redistribute the sensory activation (Figure 2) via its neural network [1]. The network dynamics is probabilistic and is modeled in this note by a transition matrix that describes how one cluster of synchronously firing neurons affects the synchronous firing rates in other clusters.

The initial face stimulation to the FFA together with a matrix defining connections of the neural network specifies a dynamical system whose stationary probability function is supported on the FFA. The stationary probability function specifies the equilibrium firing rates throughout the FFA. It is important to note that the acquisition of this probability function in the FFA happens very quickly. Among the properties of the stationary probability function are: 1) response magnitude invariance; 2) repurposing of clusters to define new probability functions on the FFA;

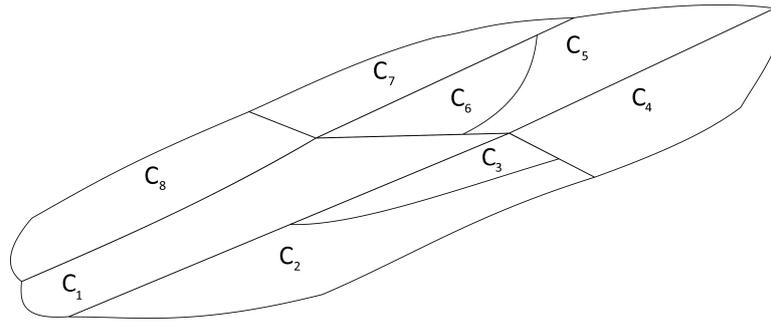


Figure 1. Partition of FFA.

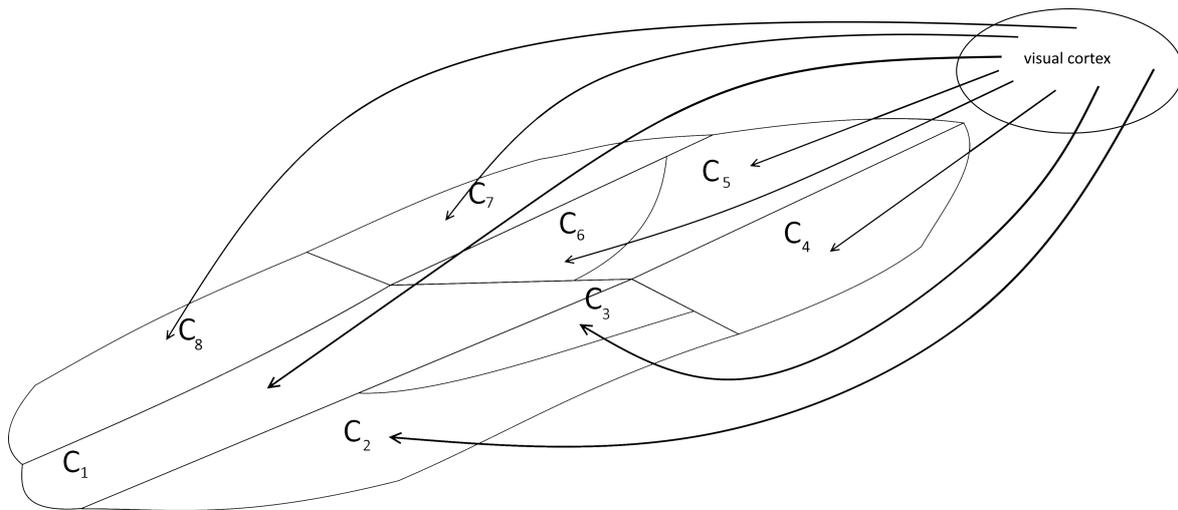


Figure 2. Initial activation of FFA.

3) stability of the stationary probability function under sensory perturbations.

A different model for computational facial encoding is developed in [21].

2. Dynamical Systems Model

Let V_i denote the volume of C_i , the region in the FFA corresponding to the i th facial feature as shown in Figure 1 and let M_i be the synchronous firing rate of the neurons in C_i . Let $S_i = M_i V_i$ which we refer to as the strength of (or total traffic coming from) the i th feature as represented in the FFA. Let $S = \sum_{i=1}^n S_i$ and define $p_i = \frac{S_i}{S}$. The collection p_1, \dots, p_n defines a probability function on the FFA since each $p_i \geq 0$ and $\sum_{i=1}^n p_i = 1$. An example of an activation pattern in the FFA is depicted in Figure 3.

The interneural network of the FFA determines how clusters interact with each other. This allows us to define transition probabilities P_{ij} , $i, j = 1, \dots, n$ where for each i the positive numbers P_{ij} sum up to 1 ($\sum_{j=1}^n P_{ij} = 1$), and are proportional to the numbers of connections from C_i to C_j via the neuronal network [1]. A sample transition matrix is shown in Figure 4. We now associate with each region C_i an interval I_i on the unit interval $[0, 1]$, then construct a piecewise linear

“semi-Markov” map [7] $\tau : [0, 1] \rightarrow [0, 1]$ on the partition $\mathcal{I} = \{I_i\}_{i=1}^n$ into n subintervals which realizes this transition probability function as shown in Figure 4. The precise definition of τ is given in the Appendix. The map τ belongs to a class of “piecewise expanding maps of the interval” [6] and in particular admits a unique stationary probability function, which can be identified with a vector $\mathbf{p} = [p_1, p_2, \dots, p_n]$. The expanding property reflects the fact that each neuron activates hundreds (even thousands) of other neurons [1]. The vector \mathbf{p} is the unique solution of n linear equation with n unknowns [6, Chapter 9]:

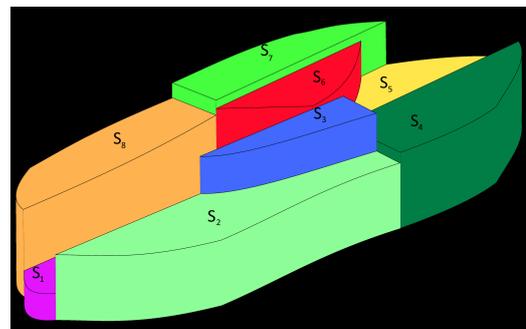


Figure 3. Sketch of FFA activation.

4.3. Stability Under Perturbations of Facial Features

Once we associate a dynamical system to a face activation on a partition of the FFA, we can study the stability of such a system. Consider a small perturbation of a face (say a laughing face or even a caricature). We want the resulting stationary probability function to be close to the original one. Such properties are proved using stability of the stationary probability function under small perturbations of the transition matrix [6]. They hold as long as most entries in the matrix are strictly positive, which corresponds to all parts of the FFA communicating between themselves [6, 14].

To illustrate the stability of \mathbf{p} under small perturbations of \mathbb{P} we give an example of a transition matrix $\mathbb{P}_1 \approx \mathbb{P}$, with perturbation ± 0.01 , and its stationary probability vector \mathbf{p}_1 . Let

$$\mathbb{P}_1 = \begin{bmatrix} 0.01 & 0.09 & 0.01 & 0.1 & 0.11 & 0.21 & 0.11 & 0.36 \\ 0.29 & 0.11 & 0 & 0.1 & 0.2 & 0.09 & 0.11 & 0.10 \\ 0.1 & 0.2 & 0.19 & 0 & 0.21 & 0.2 & 0 & 0.10 \\ 0.21 & 0 & 0.3 & 0.09 & 0.1 & 0 & 0.2 & 0.10 \\ 0.19 & 0.03 & 0.21 & 0.02 & 0.01 & 0.19 & 0.3 & 0.05 \\ 0.09 & 0.29 & 0.01 & 0.19 & 0.21 & 0 & 0.2 & 0.01 \\ 0.19 & 0.11 & 0.09 & 0.2 & 0.19 & 0.07 & 0.01 & 0.14 \\ 0.29 & 0.01 & 0.02 & 0 & 0.1 & 0.3 & 0.21 & 0.07 \end{bmatrix}$$

The stationary probability function for \mathbb{P}_1 is given by

$$\mathbf{p}_1 \approx [0.164, 0.106, 0.0931, 0.0929, 0.138, 0.136, 0.145, 0.125].$$

$$\begin{aligned} & \left(\frac{i-1}{n}, 0 \right), \left(\frac{i-1}{n} + \frac{1}{n} P_{i,1}, \frac{1}{n} \right), \\ & \left(\frac{i-1}{n} + \frac{1}{n} (P_{i,1} + P_{i,2}), \frac{2}{n} \right), \\ & \dots, \left(\frac{i-1}{n} + \frac{1}{n} (P_{i,1} + P_{i,2} + \dots + P_{i,k}), \frac{k}{n} \right), \dots, \left(\frac{i}{n}, 1 \right). \end{aligned}$$

The vertical segments of the lines are not drawn, if two consecutive points have the same x-coordinates, then the line between them is not part of the graph.

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We see that the largest difference between the components of \mathbf{p}_1 and \mathbf{p} is 0.004 (components number 5 and 7).

5. Conclusions

This note proposes a method for encoding facial identity using stationary probability function. To define such a function requires knowledge of which clusters in the FFA are activated by features of a face and the relative strengths of these activations in the FFA which depends on the respective firing rates. The FFA architecture [15] determines the transition probabilities and with the synaptic weights of the different clusters determines a flow of information, which defines the neural network dynamics. To define a transition matrix \mathbb{P} we need to know which clusters interact with other clusters. Once \mathbb{P} is known, the the map τ can be constructed and its stationary probability function and the corresponding \mathbf{p} can be calculated. We claim \mathbf{p} characterizes a face.

Appendix

In the Appendix we show how given transition probabilities P_{ij} , $i, j = 1, \dots, n$ we construct a piecewise linear "semi-Markov" map $\tau : [0, 1] \rightarrow [0, 1]$ on the partition $\mathcal{I} = \{I_i\}_{i=1}^n$ into n subintervals of equal lengths.

We will construct τ on each of the subintervals $I_i = [\frac{i-1}{n}, \frac{i}{n}]$, $i = 1, 2, \dots, n$. The graph of τ on I_i consists of segments of straight lines consecutively connecting the points:

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